

Lecture 18

LTL model checking for DTMCs and MDPs

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Overview

- Recall
 - deterministic ω -automata (DBA or DRA) and DTMCs
- LTL model checking for DTMCs
 - measurability
 - complexity
 - PCTL* model checking for DTMCs
- LTL model checking for MDPs

Recall – DBA and DRA

- Deterministic Büchi automata (DBA)
 - $(Q, \Sigma, \delta, q_0, F)$
 - accepting run must visit some state in F infinitely often
 - less expressive than nondeterministic Büchi automata (NBA)
- Deterministic Rabin automata (DRA)
 - $(Q, \Sigma, \delta, q_0, \text{Acc})$
 - $\text{Acc} = \{ (L_i, K_i) \mid 1 \leq i \leq k \}$
 - for some pair (L_i, K_i) , the states in L_i must be visited finitely often and (some of) the states in K_i visited infinitely often
 - equally expressive as NBA
 - (i.e. all ω -regular properties; and hence all LTL formulae)

Product DTMC for a DBA

- For DTMC D and DBA A

$$\text{Prob}^D(s, A) = \text{Prob}^{D \otimes A}((s, q_s), \text{GF accept})$$

– where $q_s = \delta(q_0, L(s))$

- Hence:

$$\text{Prob}^D(s, A) = \text{Prob}^{D \otimes A}((s, q_s), F T_{\text{GFaccept}})$$

– where T_{GFaccept} is the union of all BSCCs T in $D \otimes A$ with $T \cap \text{Sat}(\text{accept}) \neq \emptyset$

- Reduces to computing BSCCs and reachability probabilities

Product DTMC for a DRA

- For DTMC **D** and DRA **A**

$$\text{Prob}^D(s, A) = \text{Prob}^{D \otimes A}((s, q_s), \bigvee_{1 \leq i \leq k} (\text{FG } \neg l_i \wedge \text{GF } k_i))$$

– where $q_s = \delta(q_0, L(s))$

- Hence:

$$\text{Prob}^D(s, A) = \text{Prob}^{D \otimes A}((s, q_s), F T_{\text{Acc}})$$

– where T_{Acc} is the union of all **accepting BSCCs** in $D \otimes A$

– an **accepting BSCC** T of $D \otimes A$ is such that, for some $1 \leq i \leq k$:

- $q \models \neg l_i$ for all $(s, q) \in T$ and $q \models k_i$ for some $(s, q) \in T$
- i.e. $T \cap (S \times L_i) = \emptyset$ and $T \cap (S \times K_i) \neq \emptyset$

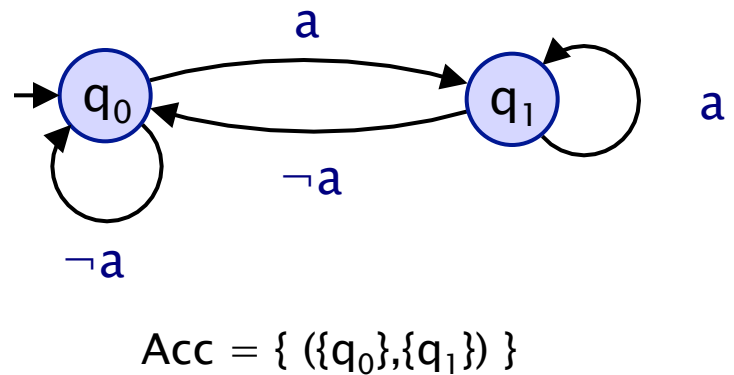
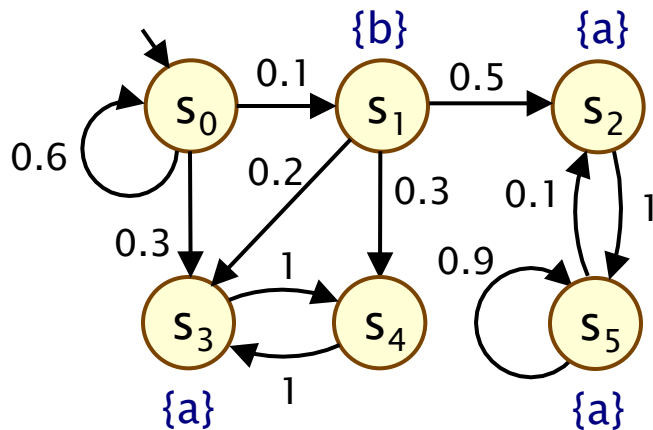
- Reduces to computing BSCCs and reachability probabilities

LTL model checking for DTMCs

- Model check LTL specification $P_{\sim p}[\psi]$ against DTMC D
- 1. Generate a deterministic Rabin automaton (DRA) for ψ
 - build nondeterministic Büchi automaton (NBA) for ψ [VW94]
 - convert the NBA to a DRA [Saf88]
- 2. Construct product DTMC $D \otimes A$
- 3. Identify accepting BSCCs of $D \otimes A$
- 4. Compute probability of reaching accepting BSCCs
 - from all states of the $D \otimes A$
- 5. Compare probability for (s, q_s) against p for each s
- Qualitative LTL model checking – no probabilities needed

Example 3 (Lec 17) revisited

- Model check $P_{>0.2} [\text{FG } a]$



- Result:

- $\text{Prob}(\text{FG } a) = [0.125, 0.5, 1, 0, 0, 1]$
- $\text{Sat}(P_{>0.2} [\text{FG } a]) = \{ s_1, s_2, s_5 \}$

Measurability of ω -regular properties

- For any ω -regular property ψ
 - the set of ψ -satisfying paths in any DTMC D is measurable
- Hence, the same applies to
 - any regular safety property
 - any LTL formula
- Proof sketch
 - any ω -regular property can be represented by a DRA A
 - we can construct $D \otimes A$, in which there is a direct mapping from any path ω in D to a path ω' in $D \otimes A$
 - $\omega \models \psi$ iff $\omega' \models \bigvee_{1 \leq i \leq k} (FG \neg l_i \wedge GF k_i)$
 - $GF \phi$ and $FG \phi$ are measurable (see lecture 3)
 - \wedge and \vee = intersection/union (which preserve measurability)

Complexity

- Complexity of model checking LTL formula ψ on DTMC D
 - is doubly exponential in $|\psi|$ and polynomial in $|D|$
 - (for the algorithm presented in these lectures)
- Converting LTL formula ψ to DRA A
 - for some LTL formulae of size n , size of smallest DRA is 2^{2^n}
- BSCC computation
 - Tarjan algorithm – linear in model size (states/transitions)
- Probabilistic reachability
 - linear equations – cubic in (product) model size
- In total: $O(\text{poly}(|D|, |A|))$
- In practice: $|\psi|$ is small and $|D|$ is large
- Complexity can be reduced to single exponential in $|\psi|$
 - see e.g. [CY88,CY95]

PCTL* model checking

- PCTL* syntax:

- $\phi ::= \text{true} \mid a \mid \phi \wedge \phi \mid \neg\phi \mid P_{\sim p} [\psi]$

- $\psi ::= \phi \mid \psi \wedge \psi \mid \neg\psi \mid X\psi \mid \psi \cup \psi$

- Example:

- $P_{>p} [GF (\text{send} \rightarrow P_{>0} [F \text{ack}])]$

- PCTL* model checking algorithm

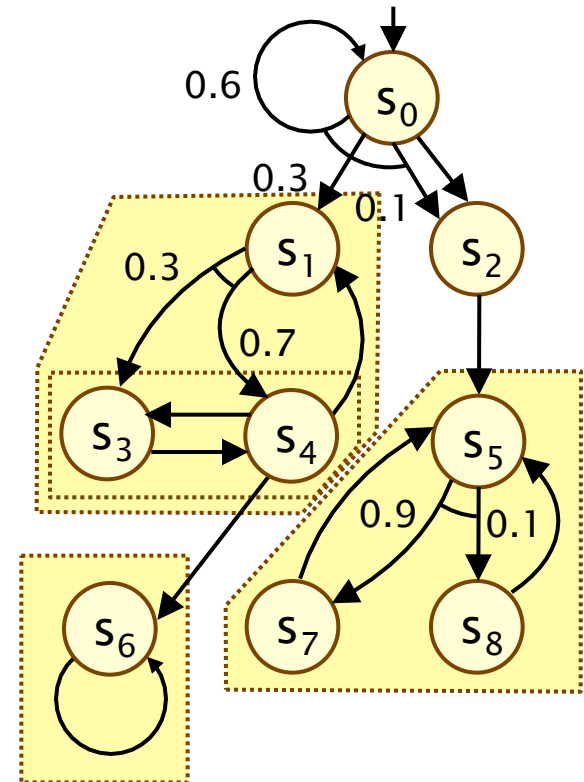
- bottom-up traversal of parse tree for formula (like PCTL)

- to model check $P_{\sim p} [\psi]$:

- replace maximal state subformulae with atomic propositions
- (state subformulae already model checked recursively)
- modified formula ψ is now an LTL formula
- which can be model checked as for LTL

Recall – end components in MDPs

- End components of MDPs are the analogue of BSCCs in DTMCs
- An end component is a strongly connected sub-MDP
- A sub-MDP comprises a subset of states and a subset of the actions/distributions available in those states, which is closed under probabilistic branching

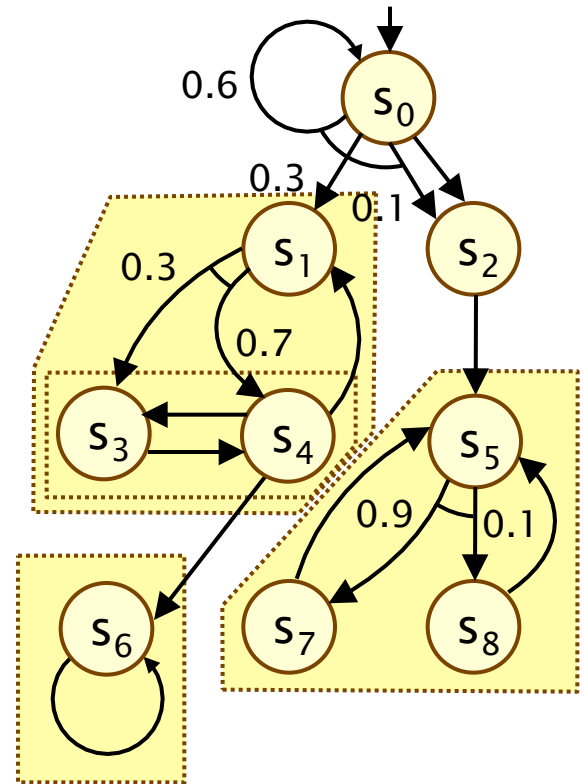


Note:

- action labels omitted
- probabilities omitted where = 1

Recall – end components in MDPs

- End components of MDPs are the analogue of BSCCs in DTMCs
- For every end component, there is an adversary which, with probability 1, forces the MDP to remain in the end component, and visit all its states infinitely often
- Under every adversary σ , with probability 1, the set of states visited infinitely often forms an end component



Recall – long-run properties of MDPs

- Maximum probabilities

- $p_{\max}(s, GF\ a) = p_{\max}(s, F\ T_{GFa})$

- where T_{GFa} is the union of sets T for all end components $(T, Steps')$ with $T \cap Sat(a) \neq \emptyset$

- $p_{\max}(s, FG\ a) = p_{\max}(s, F\ T_{FGa})$

- where T_{FGa} is the union of sets T for all end components $(T, Steps')$ with $T \subseteq Sat(a)$

- Minimum probabilities

- need to compute from maximum probabilities...

- $p_{\min}(s, GF\ a) = 1 - p_{\max}(s, FG\ \neg a)$

- $p_{\min}(s, FG\ a) = 1 - p_{\max}(s, GF\ \neg a)$

Automata-based properties for MDPs

- For an MDP M and automaton A over alphabet 2^{AP}
 - consider probability of “satisfying” language $L(A) \subseteq (2^{AP})^\omega$
 - $\text{Prob}^{M,\sigma}(s, A) = \Pr_s^{M,\sigma} \{ \omega \in \text{Path}^{M,\sigma}(s) \mid \text{trace}(\omega) \in L(A) \}$
 - $p_{\max}^M(s, A) = \sup_{\sigma \in \text{Adv}} \text{Prob}^{M,\sigma}(s, A)$
 - $p_{\min}^M(s, A) = \inf_{\sigma \in \text{Adv}} \text{Prob}^{M,\sigma}(s, A)$
- Might need minimum or maximum probabilities
 - e.g. $s \models P_{\geq 0.99} [\psi_{\text{good}}] \Leftrightarrow p_{\min}^M(s, \psi_{\text{good}}) \geq 0.99$
 - e.g. $s \models P_{\leq 0.05} [\psi_{\text{bad}}] \Leftrightarrow p_{\max}^M(s, \psi_{\text{bad}}) \leq 0.05$
- But, ψ -regular properties are closed under negation
 - as are the automata that represent them
 - so can always consider maximum probabilities...
 - $p_{\max}^M(s, \psi_{\text{bad}})$ or $1 - p_{\max}^M(s, \neg\psi_{\text{good}})$

LTL model checking for MDPs

- Model check LTL specification $P_{\sim p} [\psi]$ against MDP M
- 1. Convert problem to one needing maximum probabilities
 - e.g. convert $P_{>p} [\psi]$ to $P_{<1-p} [\neg\psi]$
- 2. Generate a DRA for ψ (or $\neg\psi$)
 - build nondeterministic Büchi automaton (NBA) for ψ [VW94]
 - convert the NBA to a DRA [Saf88]
- 3. Construct product MDP $M \otimes A$
- 4. Identify accepting end components (ECs) of $M \otimes A$
- 5. Compute **max.** probability of reaching accepting ECs
 - from all states of the $D \otimes A$
- 6. Compare probability for (s, q_s) against p for each s

Product MDP for a DRA

- For a MDP $M = (S, s_{init}, \text{Steps}, L)$
- and a (total) DRA $A = (Q, \Sigma, \delta, q_0, \text{Acc})$
 - where $\text{Acc} = \{ (L_i, K_i) \mid 1 \leq i \leq k \}$
- The product MDP $M \otimes A$ is:
 - the MDP $(S \times Q, (s_{init}, q_{init}), \text{Steps}', L')$ where:

$$q_{init} = \delta(q_0, L(s_{init}))$$

$$\text{Steps}'(s, q) = \{ \mu^q \mid \mu \in \text{Step}(s) \}$$

$$\mu^q(s', q') = \begin{cases} \mu(s') & \text{if } q' = \delta(q, L(s)) \\ 0 & \text{otherwise} \end{cases}$$

$l_i \in L'(s, q)$ if $q \in L_i$ and $k_i \in L'(s, q)$ if $q \in K_i$

(i.e. state sets of acceptance condition used as labels)

Product MDP for a DRA

- For MDP **M** and DRA **A**

$$p_{\max}^M(s, A) = p_{\max}^{M \otimes A}((s, q_s), \bigvee_{1 \leq i \leq k} (\text{FG } \neg l_i \wedge \text{GF } k_i))$$

– where $q_s = \delta(q_0, L(s))$

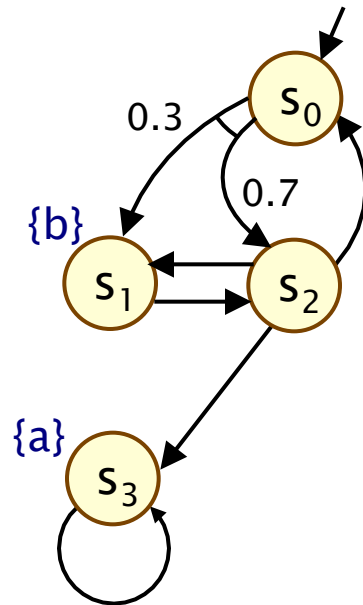
- Hence:

$$p_{\max}^M(s, A) = p_{\max}^{M \otimes A}((s, q_s), F T_{\text{Acc}})$$

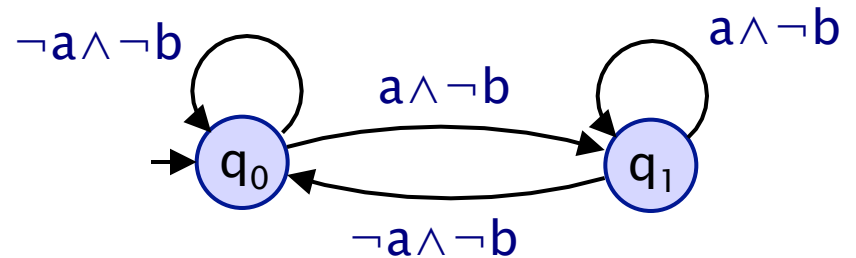
- where T_{Acc} is the union of all sets T for **accepting end components** (T, Steps') in $D \otimes A$
- an **accepting end components** is such that, for some $1 \leq i \leq k$:
 - $(s, q) \models \neg l_i$ for all $(s, q) \in T$ and $(s, q) \models k_i$ for some $(s, q) \in T$
 - i.e. $T \cap (S \times L_i) = \emptyset$ and $T \cap (S \times K_i) \neq \emptyset$

MDPs – Example 1

- Model check $P_{<0.8} [G \neg b \wedge GF a]$



DRA (in fact DBA):



$$\text{Acc} = \{ (\emptyset, \{q_1\}) \}$$

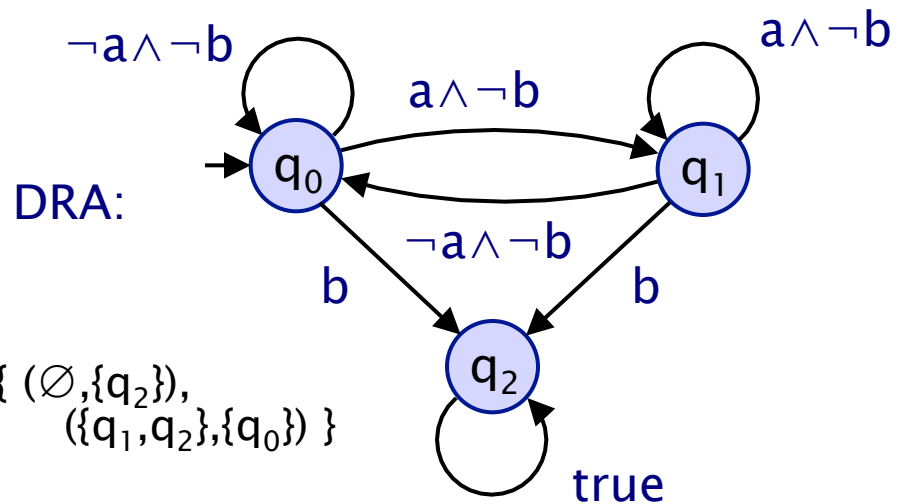
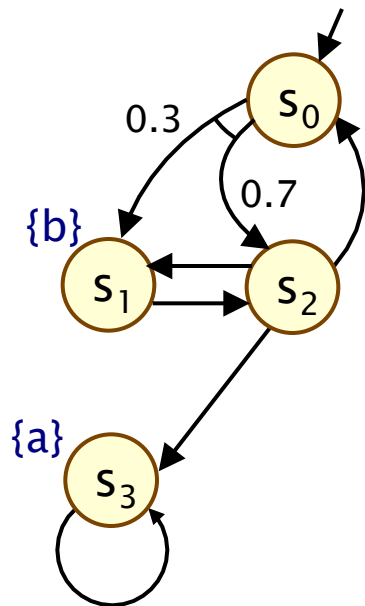
- Result:

- $\underline{p}_{\max}(G \neg b \wedge GF a) = [0.7, 0, 1, 1]$
- $\text{Sat}(P_{<0.8} [G \neg b \wedge GF a]) = \{ s_0, s_1 \}$

MDPs – Example 2

- Model check $P_{>0} [G \neg b \wedge GF a]$

$$\begin{aligned}
 - p_{\min}(s, G \neg b \wedge GF a) &= 1 - p_{\max}(s, \neg(G \neg b \wedge GF a)) \\
 &= 1 - p_{\max}(s, F b \vee FG \neg a)
 \end{aligned}$$



$$\text{Acc} = \{ (\emptyset, \{q_2\}), (\{q_1, q_2\}, \{q_0\}) \}$$

- Result: $p_{\min}(G \neg b \wedge GF a) = [0, 0, 0, 1]$
- $\text{Sat}(P_{>0} [G \neg b \wedge GF a]) = \{s_3\}$

LTL model checking for MDPs

- **Maximal** end components
 - can optimise LTL model checking using maximal end components (there may be exponentially many ECs)
- **Qualitative** LTL model checking
 - no numerical computation: use Prob1E, Prob0A algorithms
- **Complexity** of model checking LTL formula ψ on MDP M
 - is doubly exponential in $|\psi|$ and polynomial in $|M|$
 - unlike DTMCs, this cannot be improved upon
- **PCTL*** model checking
 - LTL model checking can be adapted to PCTL*, as for DTMCs
- **Optimal adversaries** for LTL formulae
 - memoryless adversary always exists for $p_{\max}(s, GF a)$ and for $p_{\max}(s, FG a)$ but not for arbitrary LTL formulae

Summing up...

- **Deterministic ω -automata (DBA or DRA) and DTMCs**
 - probability of language acceptance reduces to probabilistic reachability of set of accepting BSCCs in product DTMC
- **LTL model checking for DTMCs**
 - via construction of DRA for LTL formula
 - complexity: (doubly) exponential in the size of the LTL formula and polynomial in the size of the DTMC
 - measurability of any ω -regular property on a DTMC
- **PCTL* model checking for DTMCs**
 - combination of PCTL and LTL model checking algorithms
- **LTL model checking for MDPs**
 - max. probabilities of reaching accepting end components
 - min. probabilities through negation and max. probabilities